

Convex Combination Method on Probabilistic Fuzzy Multiobjective Transportation Problem with Pareto Distribution

Eka Susanti*, Oki Dwipurwani, Novi Rustiana Dewi, Indrawati, & Indri Yune Safira

Department of Mathematics, Universitas Sriwijaya, Indralaya Ogan Ilir South Sumatera, Indonesia

Abstract

This article introduces a transportation model with two objective functions. The first objective function is the function which minimizes the total cost and the second objective function is the function which minimizes the total time. Parameters of source, destination and maximum capacity of transportation means are assumed to follow the Pareto distribution. The multiobjective transportation model is the development of a single objective transportation model. Parameters of the objective function are expressed by triangular fuzzy numbers. Fuzzy multi objective problems are transformed into a deterministic single objective using the convex combination method. The formulated model is applied to the problem of shipping metal crates. There are 3 types of conveyances namely HDL, Engkel and Wingbox. Obtained the optimal total cost of Rp. 3,770,294 and metal crates delivery time to be for 13 hours.

Keywords: convex combination, multiobjective, transportation, pareto distribution.

1. Introduction

Transportation activity is a movement activity associated with traveling from one place to another. Transportation problems are related to transportation problems in order to find optimal cost planning from source to destination which is influenced by the distance of delivery, the number of goods to be sent, the length of time for delivery and so on (Adhami & Ahmad, 2020). In general, the purpose of transportation is to minimize the total cost or total transportation time (Chen et al., 2020), (Tang, 2020). In some cases, transportation problems have more than one objective function, for example the time and cost functions will be optimized simultaneously. Transportation problems with more than one objective function are called multiobjective transportation problems (Kakran & Dhodiya, 2020), (Bagheri et al., 2020), (Gowthami & Prabakaran, 2019), (Samanta et al., 2020), (Roy et al., 2018).

In transportation problems, there is some information that uncertainty. For example, time data and transportation cost data. The probabilistic fuzzy approach can be used to solve transportation problems with uncertainty and follow certain statistical probability distributions. Research (Kakran & Dhodiya, 2020) provides an assumption that the parameters of the transportation model follow a normal distribution. If the parameters of the transportation model do not follow a certain opportunity distribution then a stochastic approach can be used (Singh et al., 2019), (Boumediene, 2019). Other probability distributions that are often used are the exponential probability distribution (Fergany & Hollah, 2018) and the Pareto distribution (Barik, 2015). In this study, it is assumed that the constraint parameters follow the Pareto distribution. In addition to the probabilistic approach, the fuzzy approach can also be used for parameter uncertainty problems. Model parameters can be expressed as triangular fuzzy numbers (Susanti et al., 2019), hexagonal (Chakraborty et al., 2021), trapezoidal (S & S, 2020), pentagonal (Hemalatha & Annadurai, 2020). In this study, the triangular fuzzy numbers are used.

* Corresponding author.

E-mail address: xxxx@xxxxxx.edu (First Author)



Multi-objective problem can be solving by transforming into a single objective form. The convex combination method can be used. Convex combination is a concept programming method used to achieve Pareto optimal solutions of uncertain multi objective programming problems (Dalman, 2018), (Samanta et al., 2020). The optimal solution with the convex combination method is influenced by the determination of the weight values in the objective function. The combination of selecting different weight values gives a different optimal solution. Using this method, decision making has several references as a determinant of optimal policy. Other, the fuzzy programming technique can also be used to solve multiobjective problems (Kakran & Dhodiya, 2020). Matrix concepts and nonlinear programming approaches can be used to solve multiobjective problems (Roy et al., 2018), (Waliv et al., 2020). In this study, multiobjective problems were transformed into a single objective using the convex combination method where a defuzzification process using alpha-cut. The formulated probabilistic fuzzy multi objective solid transportation model is applied to the problem of transporting metal crates. Metal crate is a tool made of iron, useful as a container or storage place for synthetic rubber and natural rubber before the rubber reaches consumers, especially rubber factories around the world. there are three types of vehicles, namely HDL, engkel, and wingbox for the delivery of metal crates. Cost and delivery time data are expressed by triangular fuzzy numbers.

2. Method

The transportation problem is a problem of determining the total minimum transportation cost of a commodity with the aim of meeting demand, generally related to shipping an item from source to destination (Adhami & Ahmad, 2020). (Kakran & Dhodiya, 2020) introduced a multi objective probabilistic fuzzy solid transportation model as follows:

$$\begin{aligned} \text{Minimum } Z_1 &= \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^l \tilde{c}_{ijk} x_{ijk} \\ \text{Minimum } Z_2 &= \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^l \tilde{t}_{ijk} x_{ijk} \end{aligned}$$

Constraints:

$$\begin{aligned} \Pr\left(\sum_{j=1}^n \sum_{k=1}^l x_{ijk} - a_i \leq 0\right) &\geq \gamma_i, \quad i = 1, 2, \dots, m \\ \Pr\left(b_j - \sum_{i=1}^m \sum_{k=1}^l x_{ijk} \leq 0\right) &\geq \beta_j, \quad j = 1, 2, \dots, n \\ \Pr\left(\sum_{i=1}^m \sum_{j=1}^n x_{ijk} - e_k \leq 0\right) &\geq \delta_k, \quad k = 1, 2, \dots, l \\ x_{ijk} &\geq 0, \quad \forall i, j, k \end{aligned} \tag{1}$$

where:

- \tilde{c}_{ijk} : unit fuzzy cost source i to destination j with vehicle k
- x_{ijk} : amount of product to transport from source i to destination j with vehicle k
- \tilde{t}_{ijk} : unit fuzzy time source i to destination j with vehicle k
- a_i : stock level source i
- b_j : demand destination j
- e_k : maximum capacity vehicle k
- γ_i : level confidence of source constraint i
- β_j : level confidence of destination constraint j
- δ_k : level confidence of vehicle constraint k
- m : source
- n : destination
- l : type of vehicle

Objective function parameters and constraints are expressed by fuzzy numbers. Zadeh in (Zimmermann, 2010) defines the following fuzzy numbers.

$$\tilde{A} = \{(x, \mu_{\tilde{A}}(x)) | x \in X\} \tag{2}$$

$\mu_{\tilde{A}}(x)$ is called the membership function and lies in the interval $[0,1]$. The membership degree value can be determined

by means of a triangular curve representation. The triangular curve representation is a combination of rising linear representation and descending linear representation. The triangular fuzzy number is changed to a deterministic form using the alpha cut method.

$$r_i = (r_i - \omega_i, r_i, r_i + \omega_{i+1}) \tag{3}$$

with $\omega_i, i = 1, 2, 3, \dots$ are positif numbers and as follow $0 \leq \omega_i \leq r_i, \omega_{i+1} \geq 0$

$$\tilde{r}_i = r_i + \frac{1}{4}(\omega_{i+1} - \omega_i) \tag{4}$$

Multiobjective problems can be transformed into a single objective form using the convex combination method.

$$\text{Minimum } \sum_{i=1}^m \lambda_i E [f_i(x, \xi)] \tag{5}$$

constraint:

$$M\{g_j(x, \xi) \leq 0\} \geq \alpha_j, \quad j = 1, 2, \dots, p$$

Weighted value $\lambda_1, \lambda_2, \dots, \lambda_q$ are positif number in interval $[0, 1]$ where $\lambda_1 + \lambda_2 + \dots + \lambda_q = 1$.

3. Result and Discussion

Statistical distributions that discuss the survival of an object or individual in certain operational conditions are life test data. This analysis can be applied to the field of production related to modeling the survival of a production object in the presence of a limitation on the use of resources to produce a particular product. Reliability is referred to as the survival of production objects. In the analysis of life test data, especially for reliability, the Pareto distribution is often used. The following is the Probability Density Function (PDF) form of the Pareto distribution for two parameters (Barik, 2015).

$$f(b_i) = \frac{p_i q_i^{p_i}}{b_i^{(p_i+1)}} \tag{6}$$

by using Equation (6) it can be determined the average and the variance of the PDF, as follows:

$$\bar{b}_i = \frac{p_i q_i}{p_i - 1} \quad p_i > 1, i = 1, 2, \dots, m \tag{7}$$

and

$$Var(b_i) = \frac{p_i q_i^2}{(p_i - 1)^2 (p_i - 2)} \quad p_i > 2, i = 1, 2, \dots, m \tag{8}$$

where:

\bar{b}_i : mean

$Var(b_i)$: variance

p_i = shape parameter *ith*

q_i = scale parameter *ith*

using (2) to (8) then Model (1) can be written as follows.

$$\text{Minimum } Z_1 = \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^l c_{ijk} x_{ijk} \tag{9}$$

$$\text{Minimum } Z_2 = \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^l t_{ijk} x_{ijk}$$

Constraints:

$$\begin{aligned} \sum_{j=1}^n \sum_{k=1}^l x_{ijk} &\leq \frac{q_i}{(1-\gamma_i)^{p_i}} , i = 1,2, \dots, m \\ \sum_{i=1}^m \sum_{k=1}^l x_{ijk} &\geq \frac{q_i}{(1-\beta_j)^{p_i}} , j = 1,2, \dots, n \\ \sum_{i=1}^m \sum_{j=1}^n x_{ijk} &\leq \left(\frac{q_i}{(1-\delta_k)^{p_i}} \right) 7 , k = 1,2, \dots, l \end{aligned}$$

Model (9) is transformed into a single objective form using the convex combination method (2). Further can be written as follows.

$$\text{Min } Z = (\lambda_1 \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^l c_{ijk} x_{ijk} + \lambda_2 \sum_{i=1}^m \sum_{j=1}^n \sum_{k=1}^l t_{ijk} x_{ijk}) \quad (10)$$

constraints:

$$\begin{aligned} \sum_{j=1}^n \sum_{k=1}^l x_{ijk} &\leq \frac{q_i}{(1-\gamma_i)^{p_i}} , i = 1,2, \dots, m \\ \sum_{i=1}^m \sum_{k=1}^l x_{ijk} &\geq \frac{q_i}{(1-\beta_j)^{p_i}} , j = 1,2, \dots, n \\ \sum_{i=1}^m \sum_{j=1}^n x_{ijk} &\leq \left(\frac{q_i}{(1-\delta_k)^{p_i}} \right) 7 , k = 1,2, \dots, l \end{aligned}$$

Then the model obtained (9) and (10) is applied to the metal crate transport problem. The objective function parameter values are given in Table 1.

Inventory of metal crates at PT.Elang Marin Sentosa is 23.071. Demand for each destination respectively 160, 180, 195, 120, 160, 150, 110, 55, and 110 metal crates. As well as the payload capacity of each vehicle respectively 70, 120 and 144 metal crates.

Given $\gamma_1 = 0.01, \beta_1 = 0.06, \beta_2 = 0.05, \beta_3 = 0.05, \beta_4 = 0.04, \beta_5 = 0.06, \beta_6 = 0.05, \beta_7 = 0.06, \beta_8 = 0.04, \beta_9 = 0.05, \delta_1 = 0.05, \delta_2 = 0.06, \delta_3 = 0.07$ and $\bar{b}_1 = 13367.25; \bar{b}_2 = 262.5; \bar{b}_3 = 300; \bar{b}_4 = 267; \bar{b}_5 = 230; \bar{b}_6 = 303.7; \bar{b}_7 = 283; \bar{b}_8 = 287.5; \bar{b}_9 = 109.2; \bar{b}_{10} = 187.4; \bar{b}_{11} = 57.2; \bar{b}_{12} = 95.8; \bar{b}_{13} = 139.3; q_1 = 6802; q_2 = 160; q_3 = 180; q_4 = 195; q_5 = 120; q_6 = 160; q_7 = 150; q_8 = 110; q_9 = 55; q_{10} = 110; q_{11} = 46; q_{12} = 75; q_{13} = 122.$

based on the value and using (7) obtained value of shape parameters.

$p_1 = 2.04; p_2 = 2.56; p_3 = 2.5; p_4 = 3.71; p_5 = 2.1; p_6 = 2.1; p_7 = 2.13; p_8 = 1.62; p_9 = 2.01; p_{10} = 2.42 p_{11} = 5.1; p_{12} = 4.61; p_{13} = 8.04.$

by taking $\lambda_1 = \lambda_2 = 0.5,$

$$\begin{aligned} \text{Min } Z &= 0,5(4586x_{111} + 3092x_{112} + \dots + 3092x_{192} + 3271x_{193}) \\ &+ 0,5(0,857x_{111} + 0,708x_{112} + \dots + 0,171x_{192} + 0,694x_{193}) \end{aligned} \quad (11)$$

Constraints:

$$\begin{aligned} x_{111} + x_{112} + \dots + x_{192} + x_{193} &\leq 6835.659 \\ x_{111} + x_{112} + x_{113} &\geq 163.91282 \\ x_{121} + x_{122} + x_{123} &\geq 183.73126 \\ x_{131} + x_{132} + x_{133} &\geq 197.7159606 \\ x_{141} + x_{142} + x_{143} &\geq 122.3658 \\ x_{151} + x_{152} + x_{153} &\geq 164.7539 \\ x_{161} + x_{162} + x_{163} &\geq 154.425927 \\ x_{171} + x_{172} + x_{173} &\geq 114.2834 \\ x_{181} + x_{182} + x_{183} &\geq 56.12539 \\ x_{191} + x_{192} + x_{193} &\geq 112.35523 \end{aligned}$$

$$\begin{aligned}
 x_{111} + x_{121} + \dots + x_{181} + x_{191} &\leq 325.2554934 \\
 x_{112} + x_{122} + \dots + x_{182} + x_{192} &\leq 532.0946298 \\
 x_{113} + x_{123} + \dots + x_{183} + x_{193} &\leq 862.1780799
 \end{aligned}$$

Completion of Model (11) uses Lingo 13.0 and the following solutions are obtained.

The application of the convex combination method will provide recommendations for the number of different shipments of metal crates to each destination using 3 vehicles in order to obtain minimum costs and travel time. By taking the weight of the value λ where the value of $\lambda_1 \neq 0$, $\lambda_2 \neq 1$ and $\lambda_1 + \lambda_2 = 1$, the optimal number of metal crates will be obtained which will be distributed using different transportation vehicles. Based on Model (11), transportation costs and time will be minimized by not using HDL type vehicles.

Table 1. Fuzzy Cost and Time Parameters

Cost Parameters	TFN	Alfa Cut	Time Parameters	TFN	Alfa Cut
\widetilde{c}_{111}	(320, 320, 325)	321	\widetilde{t}_{111}	(59, 59, 63)	60
\widetilde{c}_{112}	(370, 370, 375)	371	\widetilde{t}_{112}	(84, 84, 88)	85
\widetilde{c}_{113}	(470, 470, 475)	471	\widetilde{t}_{113}	(97, 97, 106)	99
\widetilde{c}_{121}	(305, 305, 310)	306	\widetilde{t}_{121}	(54, 54, 58)	55
\widetilde{c}_{122}	(355, 355, 360)	356	\widetilde{t}_{122}	(79, 79, 83)	80
\widetilde{c}_{123}	(455, 455, 460)	456	\widetilde{t}_{123}	(92, 92, 101)	94
\widetilde{c}_{131}	(295, 295, 300)	296	\widetilde{t}_{131}	(47, 47, 50)	48
\widetilde{c}_{132}	(345, 345, 350)	346	\widetilde{t}_{132}	(71, 71, 75)	72
\widetilde{c}_{133}	(445, 445, 450)	446	\widetilde{t}_{133}	(84, 84, 92)	86
\widetilde{c}_{141}	(280, 280, 285)	281	\widetilde{t}_{141}	(44, 44, 47)	45
\widetilde{c}_{142}	(330, 330, 335)	331	\widetilde{t}_{142}	(69, 69, 72)	70
\widetilde{c}_{143}	(430, 430, 435)	431	\widetilde{t}_{143}	(82, 82, 89)	84
\widetilde{c}_{151}	(315, 315, 320)	316	\widetilde{t}_{151}	(59, 59, 61)	62
\widetilde{c}_{152}	(365, 365, 370)	366	\widetilde{t}_{152}	(84, 84, 86)	84
\widetilde{c}_{153}	(465, 465, 470)	466	\widetilde{t}_{153}	(96, 96, 104)	98
\widetilde{c}_{161}	(230, 230, 235)	231	\widetilde{t}_{161}	(28, 28, 29)	28
\widetilde{c}_{162}	(280, 280, 285)	281	\widetilde{t}_{162}	(53, 53, 54)	53
\widetilde{c}_{163}	(380, 380, 385)	381	\widetilde{t}_{163}	(66, 66, 75)	68
\widetilde{c}_{171}	(260, 260, 265)	261	\widetilde{t}_{171}	(39, 39, 45)	41
\widetilde{c}_{172}	(310, 310, 315)	311	\widetilde{t}_{172}	(64, 64, 70)	66
\widetilde{c}_{173}	(410, 410, 415)	411	\widetilde{t}_{173}	(77, 77, 90)	80
\widetilde{c}_{181}	(255, 255, 260)	256	\widetilde{t}_{181}	(39, 39, 41)	40
\widetilde{c}_{182}	(305, 305, 310)	306	\widetilde{t}_{182}	(64, 64, 66)	65
\widetilde{c}_{183}	(405, 405, 410)	406	\widetilde{t}_{183}	(77, 77, 84)	79
\widetilde{c}_{191}	(320, 320, 325)	321	\widetilde{t}_{191}	(61, 61, 65)	62
\widetilde{c}_{192}	(370, 370, 375)	371	\widetilde{t}_{192}	(85, 85, 90)	86
\widetilde{c}_{193}	(470, 470, 475)	471	\widetilde{t}_{193}	(98, 98, 105)	100

Source: PT.Elang Marin Sentosa South Sumatera

4. Conclusion

Based on the results and discussion, it is concluded that the convex combination method can be used to change multiobjective transportation problems to single objective problems. Variations in values taken as multiplier weights in convex combination method affect the optimal solution obtained. For application to metal crates shipping problems, the optimal cost and time obtained are Rp. 3,770,294 and 13 hours, respectively. The optimal number of metal crates to transport using the Engkel is 40 metal crates to the fourth destination, 165 metal crates to the fifth destination, 155 metal

crates to the sixth destination, 115 metal crates to the seventh destination, 57 metal crates to the eighth destination. Using wingbox 164 metal crates to the first destination, 184 metal crates to the second destination, 198 metal crates to the third destination, 83 metal crates to the fourth destination, and 113 metal crates to the ninth destination.

Table 2. Optimal Solution

Variable	Solution	Variable	Solution
x_{111}	0	x_{153}	0
x_{112}	0	x_{161}	0
x_{113}	164 metal crates	x_{162}	155 metal crates
x_{121}	0	x_{163}	0
x_{122}	0	x_{171}	0
x_{123}	184 metal crates	x_{172}	115 metal crates
x_{131}	0	x_{173}	0
x_{132}	0	x_{181}	0
x_{133}	198 metal crates	x_{182}	57 metal crates
x_{141}	0	x_{183}	0
x_{142}	40 metal crates	x_{191}	0
x_{143}	83 metal crates	x_{192}	0
x_{151}	0	x_{193}	113 metal crates
x_{152}	165 metal crates	x_{153}	0
Z_1	Rp 3.770.294	Z_2	12,9824 hours

Acknowledgements

The research/publication of this article was funded by DIPA of Public Service Agency of Universitas Sriwijaya 2021. SP DIPA-023.17.2.677515/2021. On November 23, 2020. In accordance with the Rector's Decree Number: 0007/UN9/SK.LP2M.PT/2021, On April 27, 2021.

References

Adhami, A. Y., & Ahmad, F. (2020). Interactive Pythagorean-Hesitant Fuzzy Computational Algorithm for Multiobjective Transportation Problem Under Uncertainty. *International Journal of Management Science and Engineering Management*, 15(4), 288–297.

Bagheri, M., Ebrahimnejad, A., Razavyan, S., Hosseinzadeh Lotfi, F., & Malekmohammadi, N. (2020). Fuzzy Arithmetic DEA Approach for Fuzzy Multi-Objective Transportation Problem. In *Operational Research*. Springer Berlin Heidelberg.

Barik, S. K. (2015). Probabilistic Fuzzy Goal Programming Problems Involving Pareto Distribution: Some Additive Approaches. *Fuzzy Information and Engineering*, 7(2), 227–244.

Boumediene, T. H. (2019). *Multi-objective interval solid transportation problem with fuzzy equality under stochastic environment*. March 2020.

Chakraborty, A., Maity, S., Jain, S., Mondal, S. P., & Alam, S. (2021). Hexagonal fuzzy number and its distinctive representation, ranking, defuzzification technique and application in production inventory management problem. *Granular Computing*, 6(3), 507–521.

Chen, K., Xin, X., Niu, X., & Zeng, Q. (2020). Coastal Transportation System Joint Taxation-Subsidy Emission Reduction Policy Optimization Problem. *Journal of Cleaner Production*, 247, 119096.

- Dalman, H. (2018). Uncertain programming model for multi-item solid transportation problem. *International Journal of Machine Learning and Cybernetics*, 9(4), 559–567.
- Fergany, H. A., & Hollah, O. M. (2018). A Probabilistic Inventory Model with Two-Parameter Exponential Deteriorating Rate and Pareto Demand Distribution. *International Journal of Scientific Research and Management*, 6(5), 31–43.
- Gowthami, R., & Prabakaran, K. (2019). Solution of Multi Objective Transportation Problem under Fuzzy Environment. *Journal of Physics: Conference Series*, 1377(1).
- Hemalatha, S., & Annadurai, K. (2020). A fuzzy EOQ inventory model with advance payment and various fuzzy numbers. *Materials Today: Proceedings*.
- Kakran, V. Y., & Dhodiya, J. M. (2020). *for Solving Uncertain Multi-objective , Multi-item Solid Transportation Problem with Linear Membership Function* (Vol. 949). Springer Singapore. Roy, S. K., Ebrahimnejad, A., Verdegay, J. L., & Das, S. (2018). New approach for solving intuitionistic fuzzy multi-objective transportation problem. *Sadhana - Academy Proceedings in Engineering Sciences*, 43(1).
- S, B. M., & S, K. (2020). Fuzzy Inventory Model with Quadratic demand, Linear Time Dependent Holding Cost, Constant Deterioration Rate and Shortages. *Malaya Journal of Matematik*, 5(1), 157–162.
- Samanta, S., Jana, D. K., Panigrahi, G., & Maiti, M. (2020). Novel Multi-Objective, Multi-Item and Four-dimensional Transportation problem with vehicle speed in LR-type intuitionistic fuzzy environment. *Neural Computing and Applications*, 32(15), 11937–11955.
- Singh, S., Pradhan, A., & Biswal, M. P. (2019). Multi-Objective Solid Transportation Problem under Stochastic Environment. *Sadhana - Academy Proceedings in Engineering Sciences*, 44(5), 1–12.
- Susanti, E., Dwipurwani, O., Sitepu, R., Wulandari, & Natasia, L. (2019). Triangular fuzzy number in probabilistic fuzzy goal programming with pareto distribution. *Journal of Physics: Conference Series*, 1282(1).
- Tang, C. H. (2020). Optimization for Transportation Outsourcing Problems. *Computers and Industrial Engineering*, 139, 106213.
- Waliv, R. H., Mishra, U., Garg, H., & Umap, H. P. (2020). A Nonlinear Programming Approach to Solve the Stochastic Multi-objective Inventory Model Using the Uncertain Information. *Arabian Journal for Science and Engineering*, 45(8), 6963–6973.
- Zimmermann, H. J. (2010). Fuzzy set theory. *Wiley Interdisciplinary Reviews: Computational Statistics*, 2(3), 317–332.